

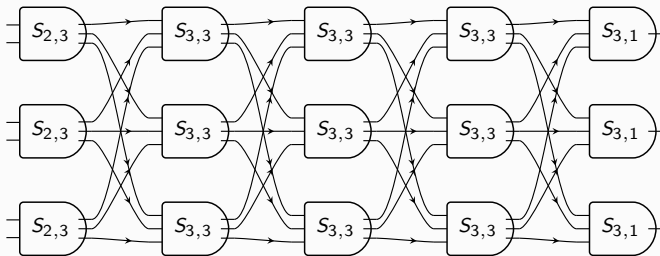
Dynamic PROPs for Networked Learners

Brandon T. Shapiro* and David I. Spivak

CALCO 2023

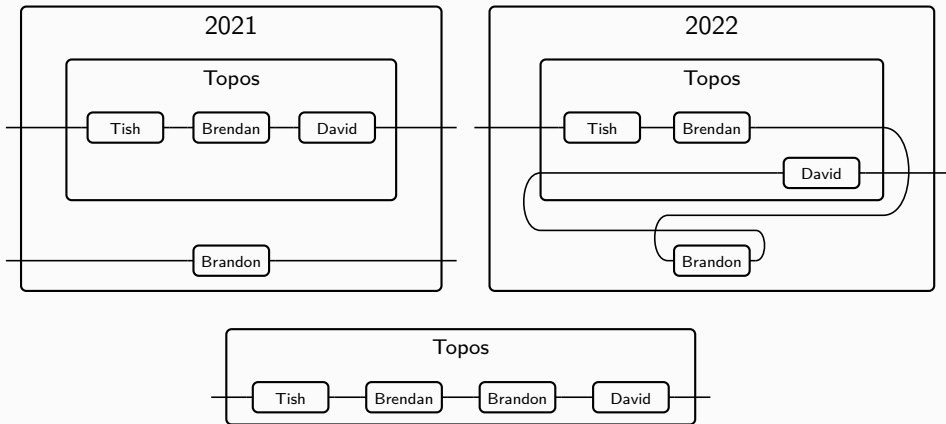


- 1 Nested dynamic structures
- 2 Polynomials and wiring diagrams
- 3 Dynamics: polynomial coalgebras
- 4 Nesting and networks: operad and PROP structure
- 5 A dynamic PROP for deep learning
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Nested dynamic structures

- How I joined Topos Institute

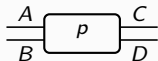


(Not an accurate representation of Topos Institute's internal structure)

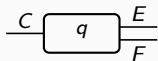
Polynomials and wiring diagrams

- Let A, B, C, D, E, F, G be sets, and consider the polynomials

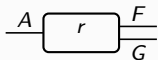
$$p = CDy^{AB}$$



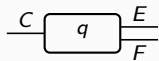
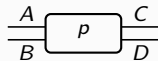
$$q = EFy^C$$



$$r = FGy^A$$



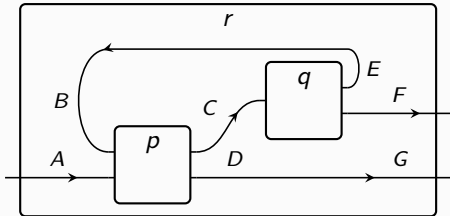
$$p \otimes q = CDEFy^{ABC}$$



- Polynomials form a category where a morphism $p \otimes q \rightarrow r$ consists of functions

$$CDEF \rightarrow FG$$

$$(CDEF)A \rightarrow ABC$$

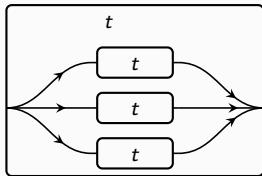


Dynamics: polynomial coalgebras

- A p -coalgebra is a set S of “states” with a function $S \rightarrow p(S)$
- For $p(S) = A \times S^B$, each state is assigned an element of A and a function $B \rightarrow S$ which updates the state
- Let $t = \mathbb{R}y^{\mathbb{R}}$ and define the polynomial $[t^{\otimes m}, t^{\otimes n}]$ as

$$\text{Hom}_{\text{Poly}}(t^{\otimes m}, t^{\otimes n})y^{\mathbb{R}^m \times \mathbb{R}^n} = \text{Hom}(\mathbb{R}^m, \mathbb{R}^n) \times \text{Hom}(\mathbb{R}^m \times \mathbb{R}^n, \mathbb{R}^m)y^{\mathbb{R}^m \times \mathbb{R}^n}$$

- A $[t^{\otimes m}, t]$ -coalgebra consists of, for each state $s \in S$, a “wiring” $t^{\otimes m} \rightarrow t$ and a “rewiring” function $\mathbb{R}^m \times \mathbb{R} \rightarrow S$



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- For deep learning:

$$S_{m,n} = \{(k \in \mathbb{N}, f: \mathbb{R}^k \times \mathbb{R}^m \rightarrow \mathbb{R}^n, r \in \mathbb{R}^k) \mid f \text{ is differentiable}\}$$

- (k, f, r) is assigned $\mathbb{R}^m \xrightarrow{f(r, -)} \mathbb{R}^n$ and

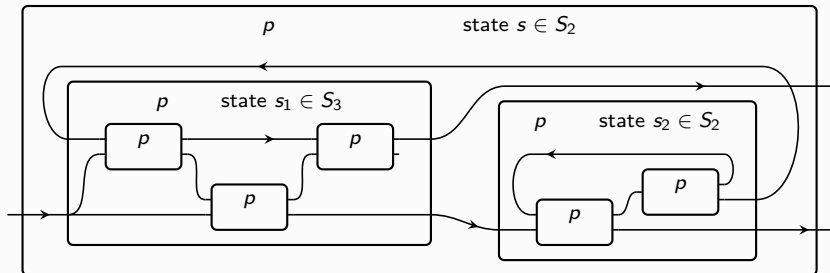
$$\mathbb{R}^m \times \mathbb{R}^n \xrightarrow{\pi_2} \mathbb{R}^n \xrightarrow{Df^T} \mathbb{R}^k \times \mathbb{R}^m \xrightarrow{\pi_2} \mathbb{R}^m$$

- the feedback $x \in \mathbb{R}^n$ causes (k, f, r) to update to

$$(k, f, r + \epsilon \pi_1 Df^T x)$$

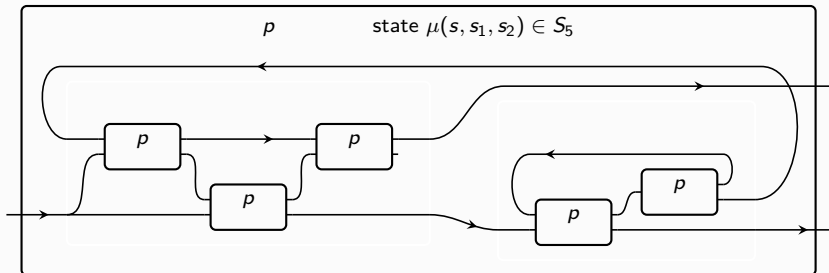
Nesting: operad structure

- A *dynamic operad* on p is a sequence of coalgebras $S_n \rightarrow [p^{\otimes n}, p](S_n)$ for all n , along with coherent functions $1 \rightarrow S_1$ and $S_n \times S_{m_1} \times \cdots \times S_{m_n} \rightarrow S_{m_1 + \cdots + m_n}$ that respect identity and composition of morphisms into p



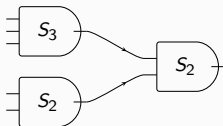
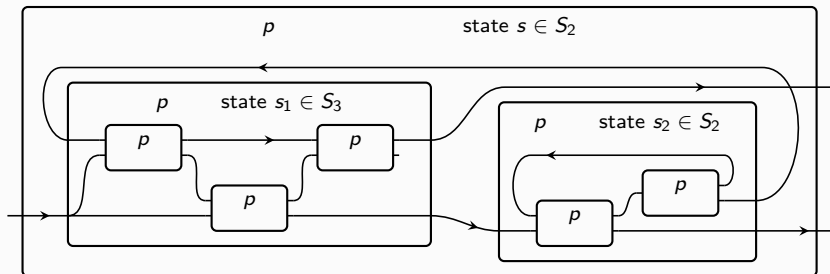
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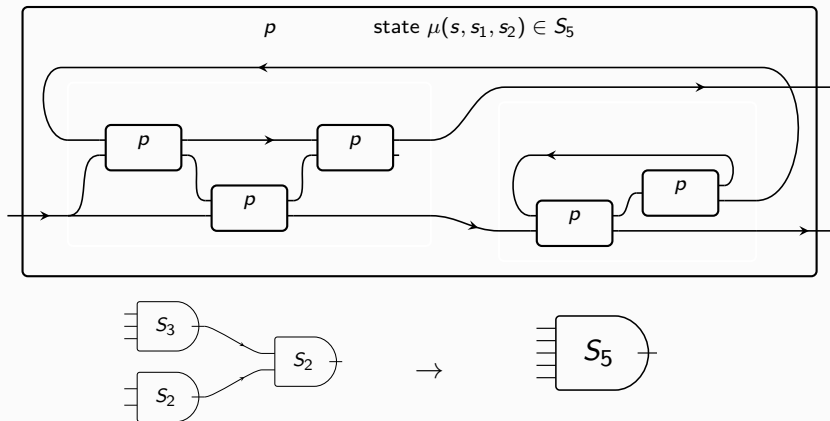
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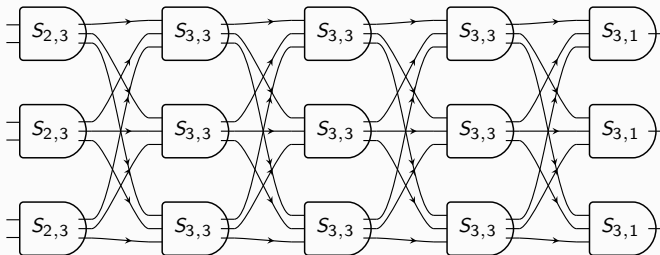
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Networks: PROP structure

- A dynamic PROP on p is a sequence of coalgebras $S_{m,n} \rightarrow [p^{\otimes m}, p^{\otimes n}](S_{m,n})$ for all m, n , along with functions $1 \rightarrow S_{1,1}$, $1 \rightarrow S_{0,0}$, $\mathbf{Perm}(m) \times \mathbf{Perm}(n) \times S_{m,n} \rightarrow S_{m,n}$
 $S_{\ell,m} \times S_{m,n} \rightarrow S_{\ell,n}$, and $S_{m_1,n_1} \times S_{m_2,n_2} \rightarrow S_{m_1+m_2,n_1+n_2}$ respecting identity/composition/tensor of morphisms into p



A dynamic PROP for deep learning

$$1 \rightarrow S_{1,1}, \quad 1 \rightarrow S_{0,0}, \quad \mathbf{Perm}(m) \times \mathbf{Perm}(n) \times S_{m,n} \rightarrow S_{m,n}$$

$$S_{\ell,m} \times S_{m,n} \rightarrow S_{\ell,n}, \quad \text{and} \quad S_{m_1,n_1} \times S_{m_2,n_2} \rightarrow S_{m_1+m_2,n_1+n_2}$$

- $S_{m,n} =$

$$\{(k \in \mathbb{N}, f: \mathbb{R}^k \times \mathbb{R}^m \rightarrow \mathbb{R}^n, r \in \mathbb{R}^k) \mid f \text{ is differentiable}\}$$

- $(0, \text{id}_{\mathbb{R}}, *)$, $(0, \text{id}_*, *)$

- $(\sigma, \tau, (k, f, r)) \mapsto$

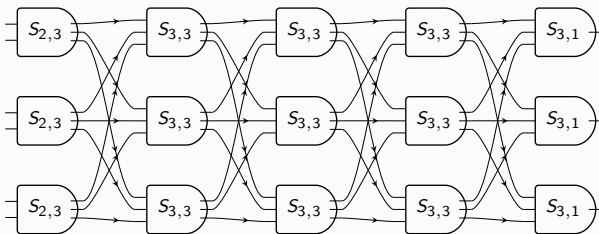
$$(k, \mathbb{R}^k \times \mathbb{R}^m \xrightarrow{\text{id} \times \mathbb{R}^\sigma} \mathbb{R}^k \times \mathbb{R}^m \xrightarrow{f} \mathbb{R}^n \xrightarrow{\mathbb{R}^\tau} \mathbb{R}^n, r)$$

- $((k', f', r'), (k, f, r)) \mapsto$

$$(k + k', \mathbb{R}^k \times \mathbb{R}^{k'} \times \mathbb{R}^\ell \xrightarrow{\text{id} \times f'} \mathbb{R}^k \times \mathbb{R}^m \xrightarrow{f} \mathbb{R}^n, (r, r'))$$

- $((k_1, f_1, r_1), (k_2, f_2, r_2)) \mapsto (k_1 + k_2, f_1 \times f_2, (r_1, r_2))$

- Model other types of learning systems compositionally as dynamic categorical structures
- As a well behaved categorical structure, dynamic PROPS can be easily compared, combined, or generalized
- Implementation in computing frameworks based on category theory or polynomials (algebraicjulia.org)



- Brandon T. Shapiro and David I. Spivak, “Dynamic operads, dynamic categories: From deep learning to prediction markets” arXiv:2205.03906
- David I. Spivak, “Learners’ Languages” arXiv:2103.01189
- Sophie Libkind and David I. Spivak, “When you light up, I light up: A dynamical monoidal category of Hebbian learners” Topos Institute Blog

Thanks!